ASM Semantics of SDL: Concepts, Methods, Tools

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Abstract State Machines

- Basic ASM Concepts
- Multi-Agent Real-Time ASM

Abstract SDL Machine

- Overall Organization
- Encoding of SDL Objects
- Operations on Signals and Timers

ASM Tool Support

Conclusions

Formal Semantics of SDL

ITU-T Recommendation Z.100 (≈ 200 pp. without Annexes)

Formal model of SDL (Meta-IV, CSP):

- · Annex F.2: Static properties of SDL (437 pp.)
- · Annex F.3: Dynamic properties of SDL (183 pp.)

Other Approaches

 $\cdot \varphi SDL$: process algebra semantics [Bergstra and Middleburg 96]

· Base SDL: Object-Z [Lau and Prinz 95]

· SDL Time Nets: extended Petri Nets [Fischer and Dimitrov 95]

· FOCUS: stream processing functions [Broy 91], [Holz and Stølen 94]

• ...

Formal Semantics of SDL

Disclaimer

Z.100, Annex F.1, p. 1:

"This annex constitutes a formal definition of SDL. If any properties of an SDL concept defined in this document, contradicts the properties defined in Z.100 and the concept is consistently defined in Z.100, then the definition in Z.100 takes precedence and this formal definition requires correction."

Overview and Motivation 1-3

ASM Semantics of SDL

Our Approach: separate specification from verification

• operational semantics

- ▷ embed a formal documentation into Z.100
- ▶ reflect the *common* understanding of SDL
- ▷ support alternative levels of abstraction

• approved meta-modelling concept

previous work:

ASM semantic of VHDL [Börger, Glässer, Müller 95]

Overview and Motivation

Abstract State Machines

BASIC ASM CONCEPTS

States

Structures with domains and functions

$$f(t_1, \dots, t_n) := t_0, \quad n \ge 0$$
 $\stackrel{Update}{\rightarrow}$ $\langle \underbrace{f^S(t_1^S, \dots, t_n^S)}_{location}, \underbrace{t_0^S}_{value} \rangle$

Update Sets

$$\Delta_S(P)$$
 program P

Computations

$$S_0 \xrightarrow{\Delta_{S_0}(P)} S_1 \xrightarrow{\Delta_{S_1}(P)} S_2 \xrightarrow{\Delta_{S_2}(P)} \cdots$$
 "pure runs"

General Abstraction Principles

Clear & Concise Specifications: "ground models"

- abstract operational views
 - ▶ hierarchical descriptions
 - ▷ incremental refinements
 - \triangleright behaviour separated from context
- information hiding & interface mechanisms

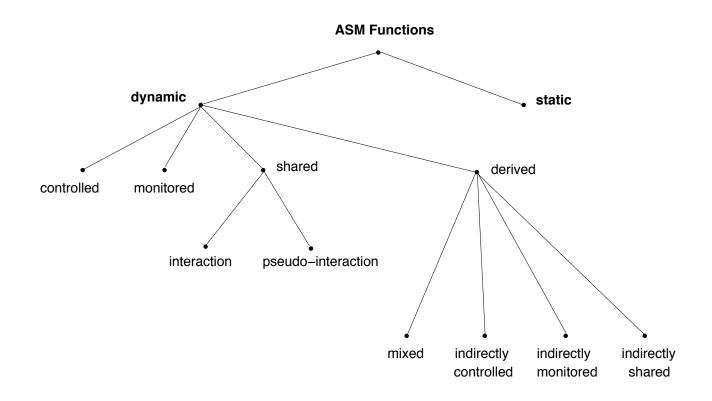
classification of ASM functions:

- static
- dynamic (controlled, monitored, shared ... global, private)

Abstract State Machines 3-1

General Abstraction Principles

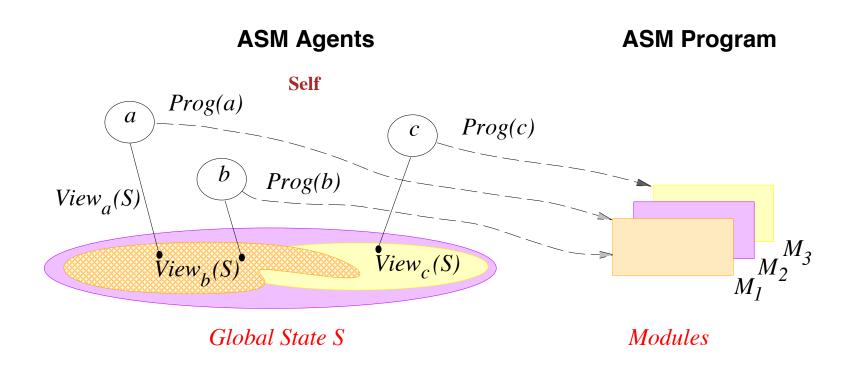
Classification of ASM Functions



Abstract State Machines 3-2

Multi-Agent Real-Time ASM

CONCURRENCY AND NONDETERMINISM



"partially ordered runs"

Multi-Agent Real-Time ASM

Multi-Agent Real-Time ASM

Global System Time

external (monitored) function:

 $now: TIME, TIME \subseteq \mathbb{R}$

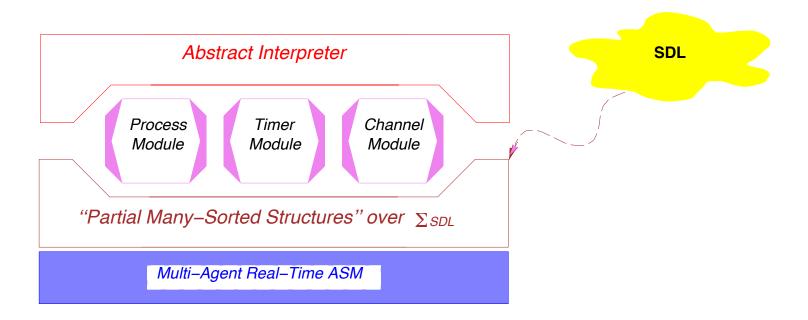
Agents perform *instantaneous* actions in *continuous* time:

An agent which is enabled at *time* t to fire a rule R actually fires R not later than $t + \epsilon$ (for some infinitely small ϵ).

Multi-Agent Real-Time ASM 4-2

Abstract SDL Machine

Interpretation Model (Basic SDL)



Encoding of SDL Objects

Static Reachability Constraints

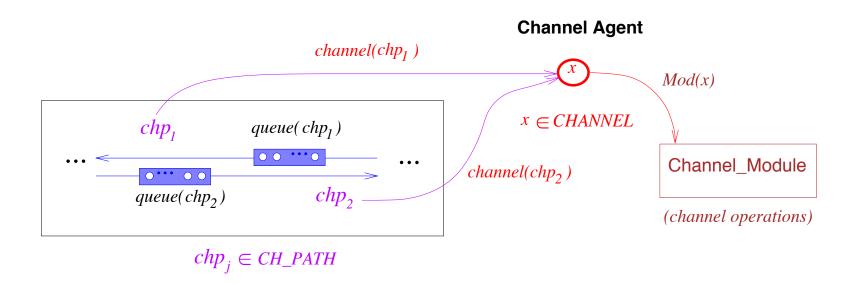
Reachability Sets

Choice of receiver and path:

 $choose_reachability: PROCESS \times SIGNAL \times \mathbf{to\text{-}Arg} \times \mathbf{via\text{-}Arg} \\ \rightarrow PATH \times RECEIVER$

Encoding of SDL Objects

Bidirectional Delaying Channel



Operations on Signals

Behaviour of Channels

```
DELIVERSIGNALS
  \equiv do forall chp: CH\_PATH(chp) \ and \ channel(chp) = Self
        if ReadyToDeliver(chp) then
           queue(chp) := tail(queue(chp))
           let si = head(queue(chp)), r = receivername(si) in
               if r = env then
                   Deliver To Env(si)
               else
                  Deliver ToProcess(si, r)
    where
        Ready To Deliver(chp)
          \equiv \exists si: SIGINST(si) \land si = head(queue(chp)) \land \neg InTransit(si, chp)
```

Operations on Signals

Behaviour of Channels (continued)

```
Deliver To Process (SInst, PName)

\equiv \text{let } PId = receiverid(SInst) \text{ in}

if PId = undef \text{ then}

\text{choose } p: PID(p) \text{ and } procname(p) = receivername(SInst)

buffer(p) := buffer(p) \land \langle SInst \rangle

else

if PID_{Sys}(PId) \text{ then}

buffer(PId) := buffer(PId) \land \langle SInst \rangle
```

Operations on Timers

Expiration Time

 $expire: TIMERINST \rightarrow TIME$

Behaviour of Timers

```
Active(t) \equiv \\ ActiveTime(t) \lor ActiveSignal(t) \\ ActiveTime(t) \equiv \\ TIMERINST(t) \land expire(t) \neq undef \\ ActiveSignal(t) \equiv \\ TIMERINST(t) \land \exists \ s \in SIGINST: \ t = timer(s) \land s \ in \ buffer(owner(t)) \\ ActiveSignal(t) \Rightarrow \\ TIMERINST(t) \land \exists \ s \in SIGINST: \ t = timer(s) \land s \ in \ buffer(owner(t)) \\ ActiveSignal(t) \Rightarrow \\ TIMERINST(t) \land \exists \ s \in SIGINST: \ t = timer(s) \land s \ in \ buffer(owner(t)) \\ ActiveSignal(t) \Rightarrow \\ TIMERINST(t) \land \exists \ s \in SIGINST: \ t = timer(s) \land s \ in \ buffer(owner(t)) \\ ActiveSignal(t) \Rightarrow \\ TIMERINST(t) \land \exists \ s \in SIGINST: \ t = timer(s) \land s \ in \ buffer(owner(t)) \\ ActiveSignal(t) \Rightarrow \\ TIMERINST(t) \land \exists \ s \in SIGINST: \ t = timer(s) \land s \ in \ buffer(owner(t)) \\ ActiveSignal(t) \Rightarrow \\ TIMERINST(t) \land \exists \ s \in SIGINST: \ t = timer(s) \land s \ in \ buffer(owner(t)) \\ ActiveSignal(t) \Rightarrow \\ TIMERINST(t) \land \exists \ s \in SIGINST: \ t = timer(s) \land s \ in \ buffer(owner(t)) \\ ActiveSignal(t) \Rightarrow \\ TIMERINST(t) \land \exists \ s \in SIGINST: \ t = timer(s) \land s \ in \ buffer(owner(t)) \\ ActiveSignal(t) \Rightarrow \\ TIMERINST(t) \land \exists \ s \in SIGINST: \ t = timer(s) \land s \ in \ buffer(owner(t)) \\ ActiveSignal(t) \Rightarrow \\ TIMERINST(t) \land \exists \ s \in SIGINST: \ t = timer(s) \land s \ in \ buffer(owner(t)) \\ ActiveSignal(t) \Rightarrow \\ TIMERINST(t) \land \exists \ s \in SIGINST: \ t = timer(s) \land s \ in \ buffer(owner(t)) \\ ActiveSignal(t) \Rightarrow \\ TIMERINST(t) \land \exists \ s \in SIGINST: \ t = timer(s) \land s \ in \ buffer(owner(t)) \\ ActiveSignal(t) \Rightarrow \\ TIMERINST(t) \land \exists \ s \in SIGINST(t) \\ ActiveSignal(t) \Rightarrow \\ TIMERINST(t) \land s \Rightarrow
```

Operations on Timers

Operations on Timers

TIMER OPERATION

```
\equiv if MyAction(Self) then if Action = set then let time = fst(Arg) in SETEXPIRATIONTIME(time) DISCARDTIMERSIGNAL else if Active(Self) then expire(Self) := undef DISCARDTIMERSIGNAL
```

else

if $ActiveTime(Self) \land now \ge expire(Self)$ then expire(Self) := undef CREATETIMERSIGNAL

Operations On Timers

Behaviour of Timers (continued)

```
\begin{split} & \equiv \text{if } \textit{Time} = \textit{undef then} \\ & = \textit{expire}(\textit{Self}) := \textit{now} + \textit{duration}(\textit{timername}(\textit{Self})) \\ & = \text{elif } \textit{Time} \leq \textit{now then} \\ & = \textit{expire}(\textit{Self}) := \textit{undef} \\ & = \text{CREATETIMERSIGNAL} \\ & = \text{else} \\ & = \textit{expire}(\textit{Self}) := \textit{Time} \end{split}
```

Conclusions

Observations

- SDL view and ASM view of distributed "real-time" systems coincide:
 - ▷ notions of *concurrency*, *reactivity* and *time* are tightly related;
 - \triangleright common understanding of SDL can *directly* be formalized.
- ASM semantics of Basic SDL
 - \triangleright is particularly *concise*, readable and understandable;
 - ▷ can easily be extended and modified;
 - \triangleright bridging semantics for combining SDL with other languages.

Further References

http://www.uni-paderborn.de/cs/asm/